Model uncertainty in FHS risk models

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- 1 The problem
- 2 FHS and backtesting models
- 3 Estimating parameter uncertainty
- 4 Conclusions

General modelling steps:

- Determine a statistical model which describes P&L dynamics. Example: GARCH(1,1) parameters estimated using MLE over a given estimation window.
- Selected a risk measure θ (e.g. VaR), and estimate a θ -point forecast at a fixed horizon.
- Test the model: Create a time series of forecasts obtained using a rolling window and compare with realized P&L at each point (backtesting).
- Apply some statistical test to interpret the backtesting results (i.e. assess, with certain confidence level, whether the model captures the true risk).



	CCP's
Statistical model	FHS with EWMA
describing P&L	volatility estimates
dynamics	over a +5yr window.
Estimate a ϕ point	VaR of CVaR, 2 to
forecast for a fixed	7 day MPOR, 99%
horizon.	or 99.5% confidence
	level
Backtesting	Count exceptions
	over >1yr window
Statistical test to in-	Kupiec's and
terpret the backtest-	Christoffersen's
ing results	tests.

The problem

	CCP's	Model risk
Statistical model describing P&L	FHS with EWMA volatility estimates	Wrong model, pa- rameter estimation
dynamics	over a $+5$ yr window.	error
Estimate a ϕ point	VaR of CVaR, 2 to	Inadequate risk
forecast for a fixed	7 day MPOR, 99%	measure or MPOR
horizon.	or 99.5% confidence	
	level	
Backtesting	Count exceptions over 2 to 5yr window	Inadequate testing model
Statistical test to in-	Kupiec's and	
terpret the backtest-	Christoffersen's	
ing results	tests.	

	CCP's	Model risk	Questions
Statistical model describing P&L dynamics	FHS with EWMA volatility estimates over a +5yr window.	Wrong model, parameter estimation error	Can we quantify uncertainty around the choice of parameters?
Estimate a ϕ point forecast for a fixed horizon.	VaR of CVaR, 2 to 7 day MPOR, 99% or 99.5% confidence level	Inadequate risk measure or MPOR	
Backtesting	Count exceptions over 2 to 5yr window	Inadequate testing model	How powerful are the tests? Is back- testing the right ap- proach?
Statistical test to in- terpret the backtest- ing results	Kupiec's and Christoffersen's tests.		



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Aim is to incorporate a volatility updating scheme to increase the sensitivity of historical simulation models to the arrival of new information.

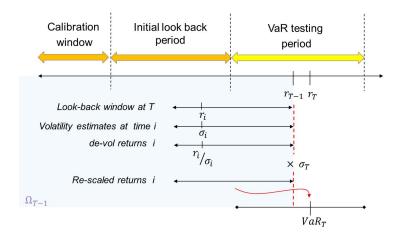
- Aim is to incorporate a volatility updating scheme to increase the sensitivity of historical simulation models to the arrival of new information.
- Common approaches are variants of the Filtered Historical Simulation (FHS) methods suggested by John Hull and Allan White (1998) and Barone-Adesi, Bourgoin and Giannopoulos (1998).

Filtered samples

- Aim is to incorporate a volatility updating scheme to increase the sensitivity of historical simulation models to the arrival of new information.
- Common approaches are variants of the Filtered Historical Simulation (FHS) methods suggested by John Hull and Allan White (1998) and Barone-Adesi, Bourgoin and Giannopoulos (1998).
- Examples: initial margin methodologies for interest rate products used by LCH Swapclear, CME and Eurex (Gregory, 2014).



FHS



EWMA volatility estimates

- The conditional volatility estimates derived from an EWMA volatility updating scheme or from a GARCH process.
- EWMA recursive formula:

$$\sigma_{t+1}^2 = \lambda \sigma_t^2 + (1 - \lambda)r_t^2 \tag{1}$$

The decay factor, $\lambda \in [0,1]$, determines the responsiveness of the process to the arrival of new information.



Is backtesting (+ Kupiec + Christoffersen) the correct tool?

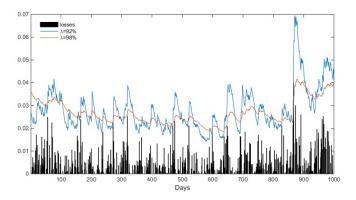


Figure : Backtesting of FHS VaR estimates for SPX using decay factors $\lambda = 0.92$ and $\lambda = 0.98$. Both cases produce 5 exceptions (which is exactly what the model predicts at 99.5% confidence). Both models pass the Kupiec's and Christoffersen's tests.



- Hypothesis tests are largely insensitive to the dynamics resulting from different decay factors.
- They tend to favor overreacting calibrations, especially at high coverage levels, which is an undesirable outcome in terms of the procyclicality.
- Asymmetric piece-wise linear (APL) score functions improve performance, which is in line with Gneiting (2012) (applying scoring functions which are consistent for the α -quantile functional).
- Calibration and validation of the model cannot only rely on backtesting, even when accounting for the size and duration of the exceptions, and additional criteria needs to be considered.



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- The problem: Quantify the impact of parameter uncertainty on the output of VaR models that rely on EWMA volatility estimates, including its sensitivity to the time period considered.
- Why it is important: Quantifying the uncertainty of those outputs can help the risk manager take more informed and transparent decisions about the amount of initial margin required.
- What we do: We apply a Bayesian approach to quantify parameter uncertainty in EWMA-based VaR models.



Why Bayesian?

- Classical (frequentist) approach:
 - In general not well-suited to answer questions of parameter uncertainty because the only uncertainty they deal with is in sampling.
 - One typically identifies point estimates, such the MLE, of certain model parameters and, in doing so, overlooks the stochastic nature of the estimation of these parameters.
- Bayesian estimation:
 - Point estimates for parameters are substituted by probability distributions that describe the uncertainty surrounding the estimation process.
 - Allows the modeller to incorporate their prior knowledge.
 - The outcome is a joint posterior distribution of the model parameters and the projected portfolio outcomes.



EWMA process is a particular case of an integrated GARCH process (IGARCH), as defined by Engle and Bollerslev (1986). In general, an IGARCH(1,1) process has the following specification:

$$\sigma_t^2 = \omega_0 + \lambda \sigma_{t-1}^2 + (1 - \lambda) r_{t-1}^2$$

$$r_t \sim \mathcal{G}(0, \sigma_t)$$
(2)

Estimating parameter uncertainty

where $\mathcal{G}(0,\sigma_t)$ is a standardized distribution and ω_0 is the drift parameter. In our analysis, we will assume the drift is zero, so that the conditional volatility in (2) is an EWMA process.¹

¹Although a zero-drift IGARCH process has the undesirable property of converging almost surely to zero (Nelson, 1990), this should not be a problem when working at short term horizons. 4日 > 4周 > 4 至 > 4 至 >

We expand the IGARCH specification with zero-drift by converting the exogenous parameters λ and σ_0 into internal parameters that are modelled as random variables

$$(\lambda, \sigma_0) \sim p(\lambda, \sigma_0)$$

$$(\sigma_t^2 | \lambda, \sigma_0) = \lambda^t \sigma_0^2 + (1 - \lambda) \sum_{i=1}^t r_{i-1}^2 \lambda^{t-i}$$

$$(r_t | \sigma_t^2) \sim \mathcal{G}(0, \sigma_t)$$
(3)

Let \hat{r}_i be a set of observed returns. We apply Bayes' rule

$$p(\lambda, \sigma_0 | \hat{r}_1, ..., \hat{r}_T) = \frac{p(\lambda, \sigma_0) \times p(\hat{r}_1, ..., \hat{r}_T | \lambda, \sigma_0)}{p(\hat{r}_1, ..., \hat{r}_T)}$$
(4)

Estimating parameter uncertainty

This posterior distribution can then be used to forecast the next unknown observable, r_{T+1} . These forecasts are the posterior predictive distributions and are expressed as a weighted average of the model's conditional predictions weighted by the posterior:

$$p(r_{T+1}|\hat{r}_T, ..., \hat{r}_1) = \int_0^\infty \int_0^1 p(r_{T+1}|\lambda, \sigma_0) p(\lambda, \sigma_0|\hat{r}_T, ..., \hat{r}_1) d\lambda d\sigma_0$$
(5)

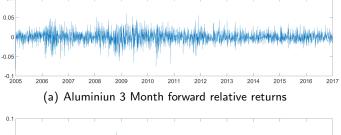


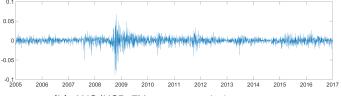
- The magnitude of the parameter uncertainty around λ for some typical market risk factors,
- The resulting uncertainty in the model's forecasts and on its accuracy,
- The impact of market data sample size on the level of uncertainty around λ .



Data: daily returns covering a 12-year period, from 3 January 2005 to 30 December 2016.

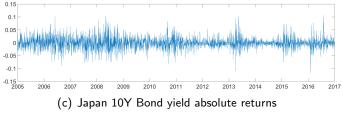
Estimating parameter uncertainty

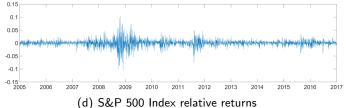




(b) AUS/USD FX spot rate relative returns







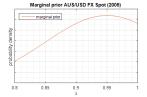


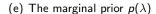
Prior distributions (chosen to match our prior information):

• $p(\lambda)$ is defined as a truncated normal distribution, with mean 0.95 and standard deviation 0.1, which is truncated outside the range $0.8 \le \lambda \le 1$ (and re-normalised);

Estimating parameter uncertainty

■ $p(\sigma_0)$ is defined as a gamma distribution, with shape parameter 2 and scale parameter 1, so that the peak value is at 1% and the standard deviation is $\sqrt{2}$.



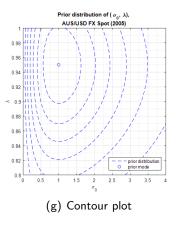


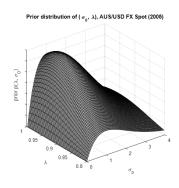


(f) The marginal prior $p(\sigma_0)$



Prior joint distribution:





(h) Joint distribution

Estimation based on the approach proposed by Nakatsuma (1998): For each parameter pair (λ, σ_0) we express the joint distribution as a product of densities for each individual return, where each density is conditioned on the preceding returns:

$$p(\hat{r}_0, ..., \hat{r}_T | \lambda, \sigma_0) = p(\hat{r}_0 | \lambda, \sigma_0) \times p(\hat{r}_1 | \hat{r}_0, \lambda, \sigma_0) \times ...$$
(6)
... \times p(\hat{r}_T | \hat{r}_0, ..., \hat{r}_{T-1}, \lambda, \sigma_0)

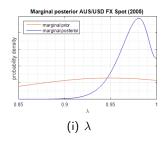


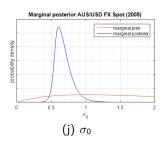
■ In more complex models with larger parameter spaces this is typically achieved by Markov-Chain Monte Carlo (MCMC) sampling.

- In our model, the parameter space is small enough to allow direct computation of the posterior on a grid of values in parameter space.
- Grid consisting of 2,001 uniformly-spaced points between $\lambda = 0.8$ and 1 (inclusive), and 1,501 uniformly-spaced points between $\sigma_0 = 0$ (exclusive) and an upper value that is 4% where relative returns are used, or 8 bps where absolute returns are used.
- The posterior is calculated directly at each grid point in parameter space and then normalising over the entire space.

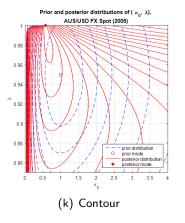


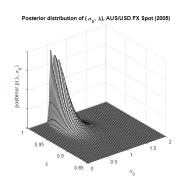
Marginal posterior (AUS/USD)





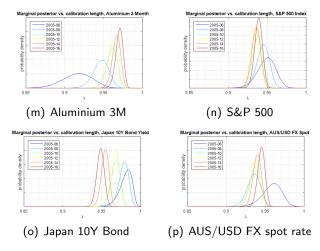
Posterior $p(\lambda, \sigma_0)$



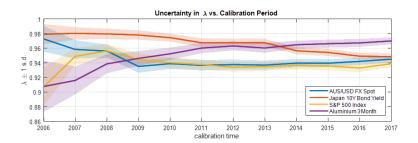


(I) Joint

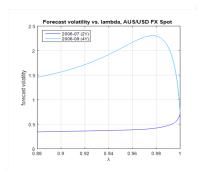
Evolution over time of the mean and standard deviations of marginal posteriors.

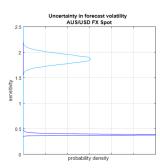


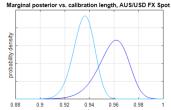
Evolution of the mean and standard deviation of the marginal posterior distributions $p(\lambda|\text{data})$ for six selected time periods.



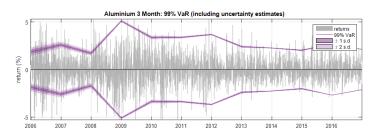
The propagation of uncertainty into the model's outcome



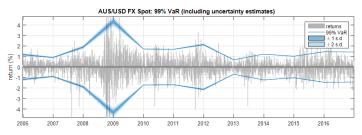




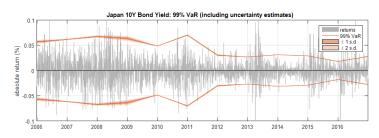




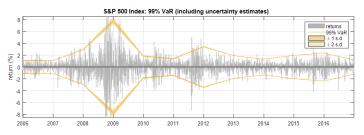
(q) Aluminium 3 Month 1-day relative returns



(r) AUS/USD FX spot 1-day relative returns



(s) Japan 10Y Bond yield 1-day absolute returns



(t) S&P 500 Index 1-day relative returns

Dispersion of the marginal posterior distributions, using the standard deviation of this distribution as a metric for parameter uncertainty.

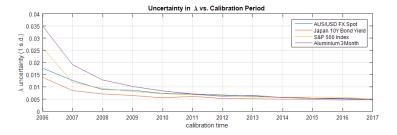


Figure: Plots of the standard deviations of the posterior distributions $p(\lambda|\hat{r}_0,...,\hat{r}_T)$ for all six time periods and all four data series. The points have been linearly joined only for illustration purposes.



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- Bayesian inference provides a useful framework for modelling parameter uncertainty in EWMA estimates.
- The model specification appears unstable, which reduces confidence in using the EWMA-VaR approach to accurately estimate quantile measures of risk.
- Propagation method causes more variation in prediction uncertainty than changes in parameter uncertainty, over time.



- Understanding and monitoring such uncertainty may help improving risk management practices in various ways. In the case of CCPs, for example by
 - Considering richer processes for the evolution of returns.
 - Articulating a model risk tolerance by specifying what could be the maximum acceptable amount of uncertainty around the model outputs.
 - Monitoring uncertainty around outputs and use it as key indicator of potential model failure.
- The benefits of model accuracy should be balanced against other priorities as, for example, the economic cost of calling additional resources, or the importance of calibrating models in a way that they are not prone to overreacting.





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